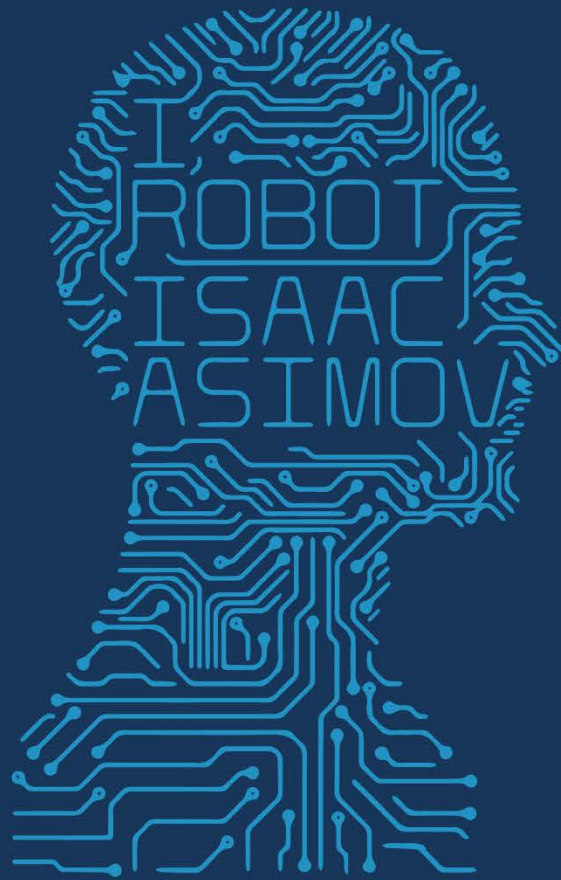


Pattern Recognition

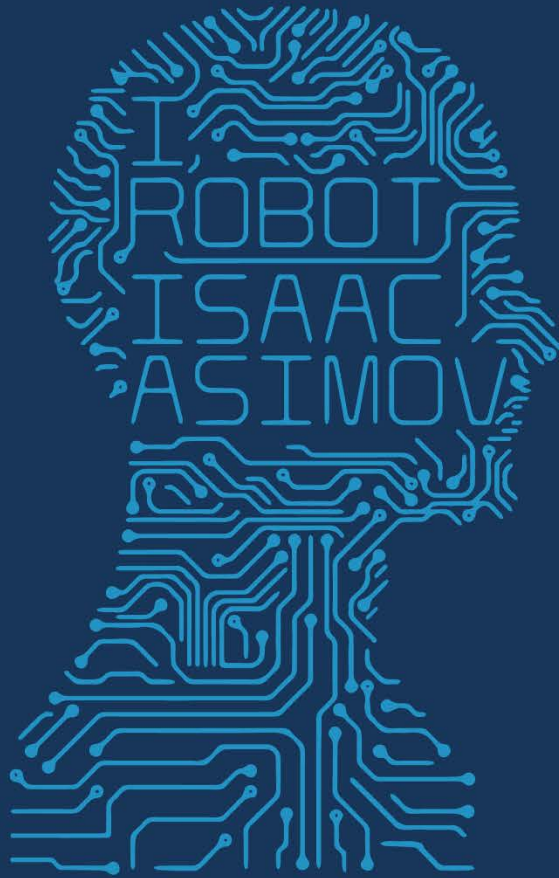
Dr.Ahmed Anter

Senior Lecture, Computer Science Dep.,
Faculty of Computer Science



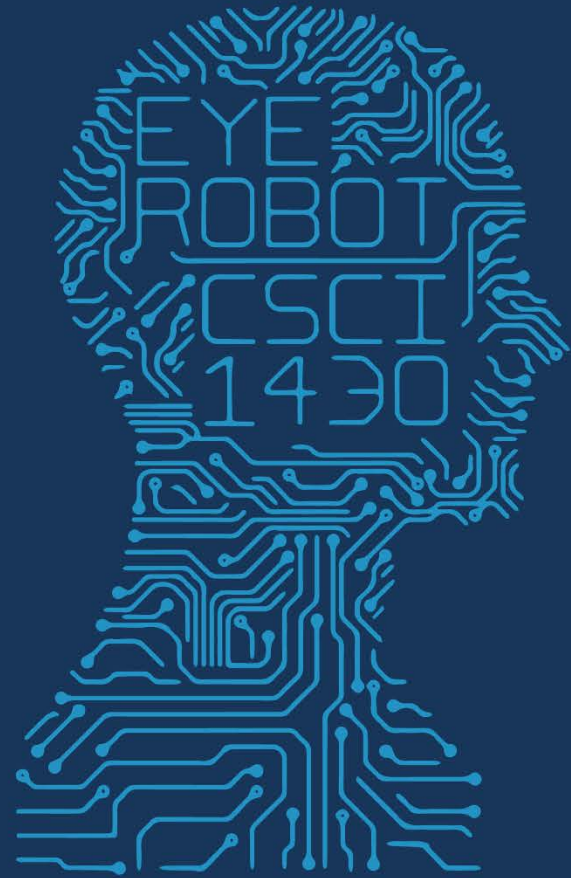
1950

FUTURE VISION



1950

FUTURE VISION



2017 MWF 1PM

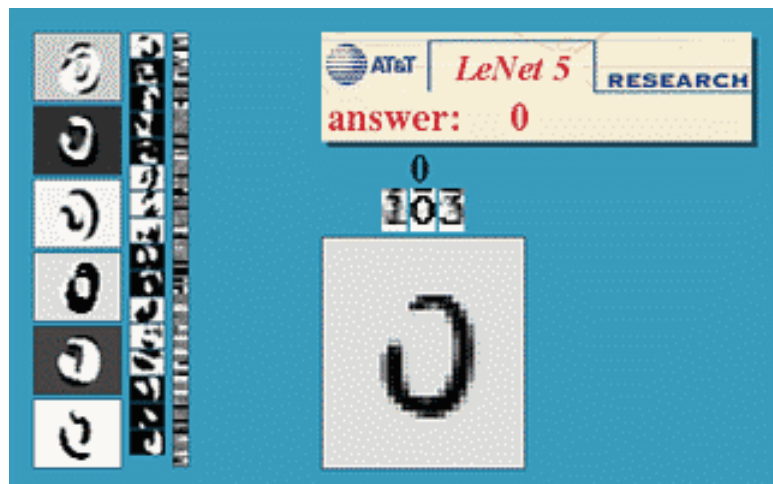
COMPUTER VISION

Projects

Optical character recognition (OCR)

Technology to convert scanned docs to text

- If you have a scanner, it probably came with OCR software



Digit recognition, AT&T labs

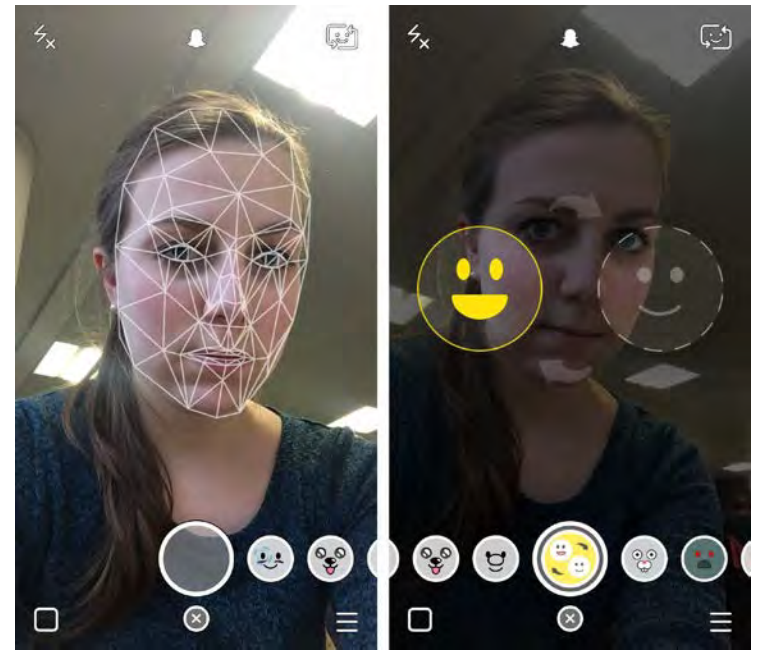
<http://www.research.att.com/~yann/>



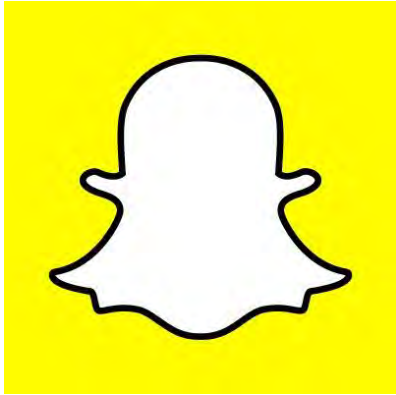
License plate readers

http://en.wikipedia.org/wiki/Automatic_number_plate_recognition

Face detection



- Almost all digital cameras detect faces
- Snapchat face filters



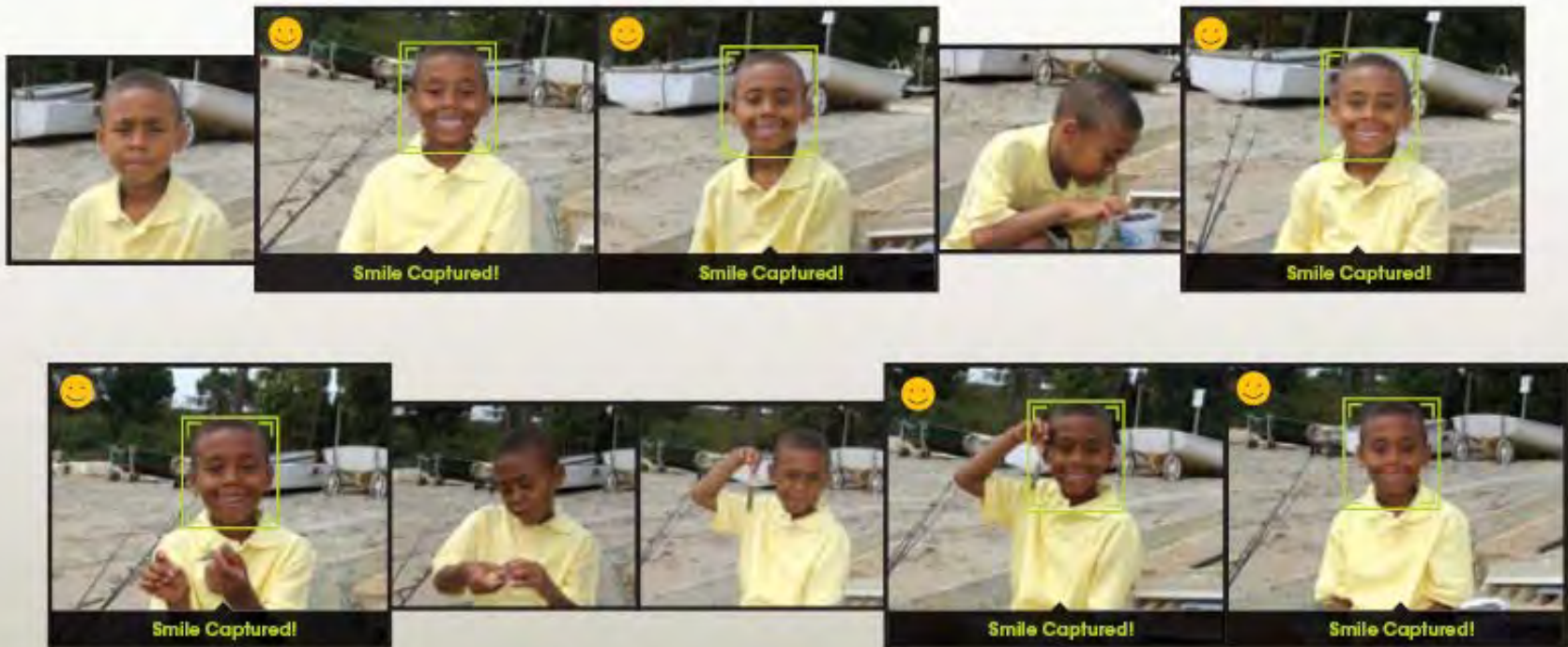




Smile detection

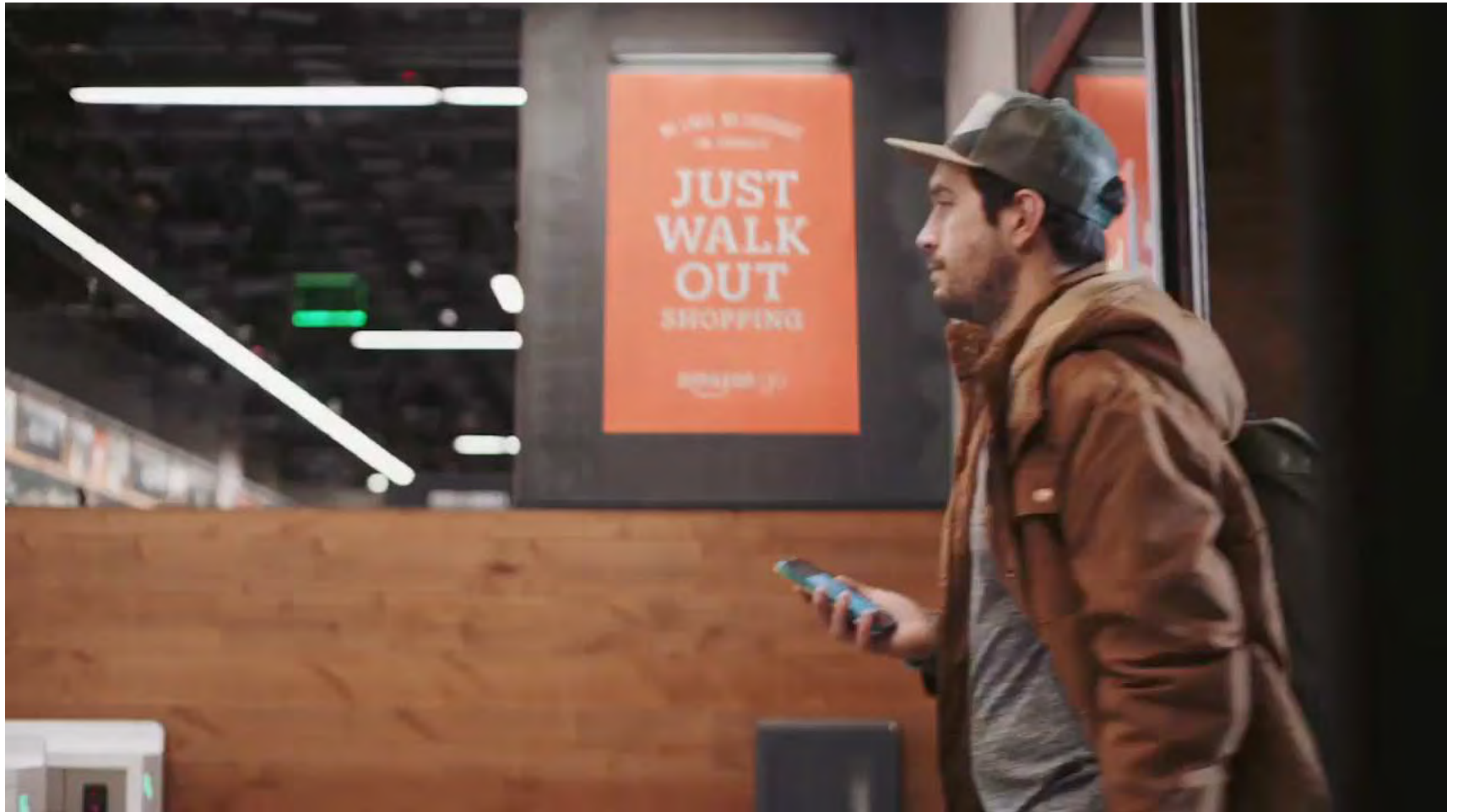
The Smile Shutter flow

Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



[Sony Cyber-shot® T70 Digital Still Camera](#)

Object recognition (in supermarkets)

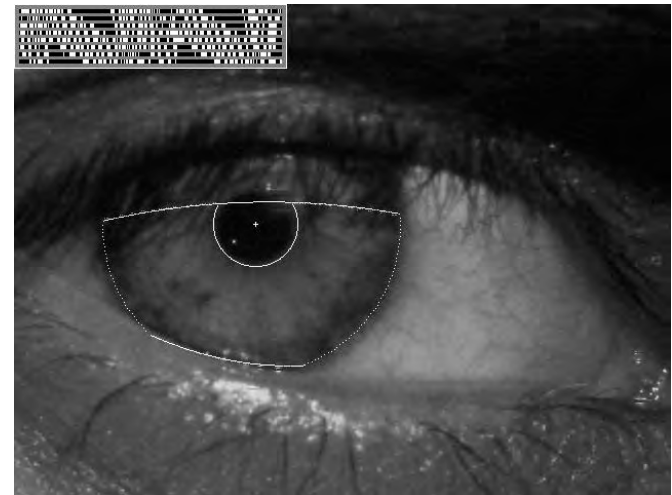
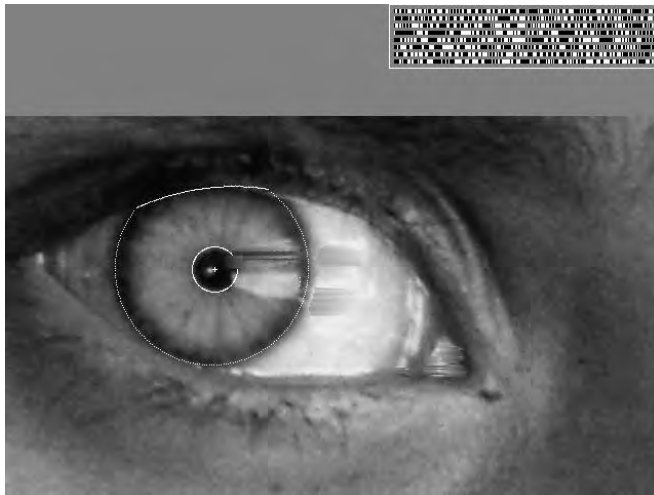


Vision-based biometrics

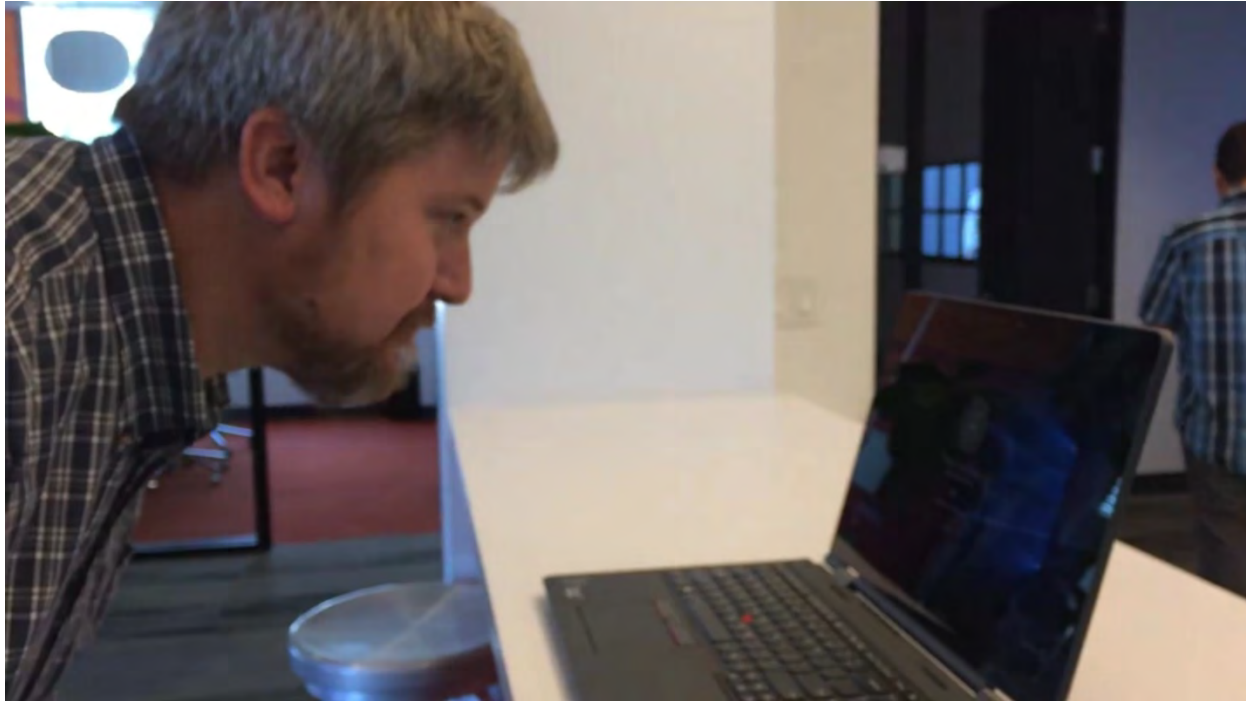


“How the Afghan Girl was Identified by Her Iris Patterns”

Read the [story](#) ([Wikipedia](#))



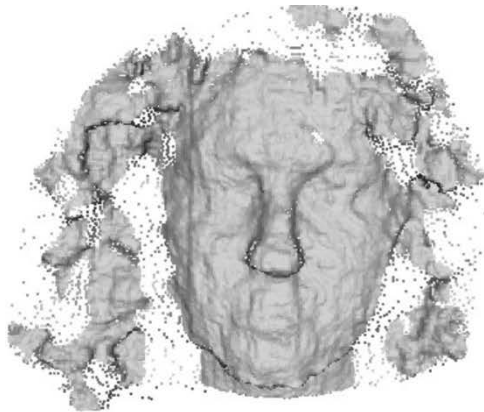
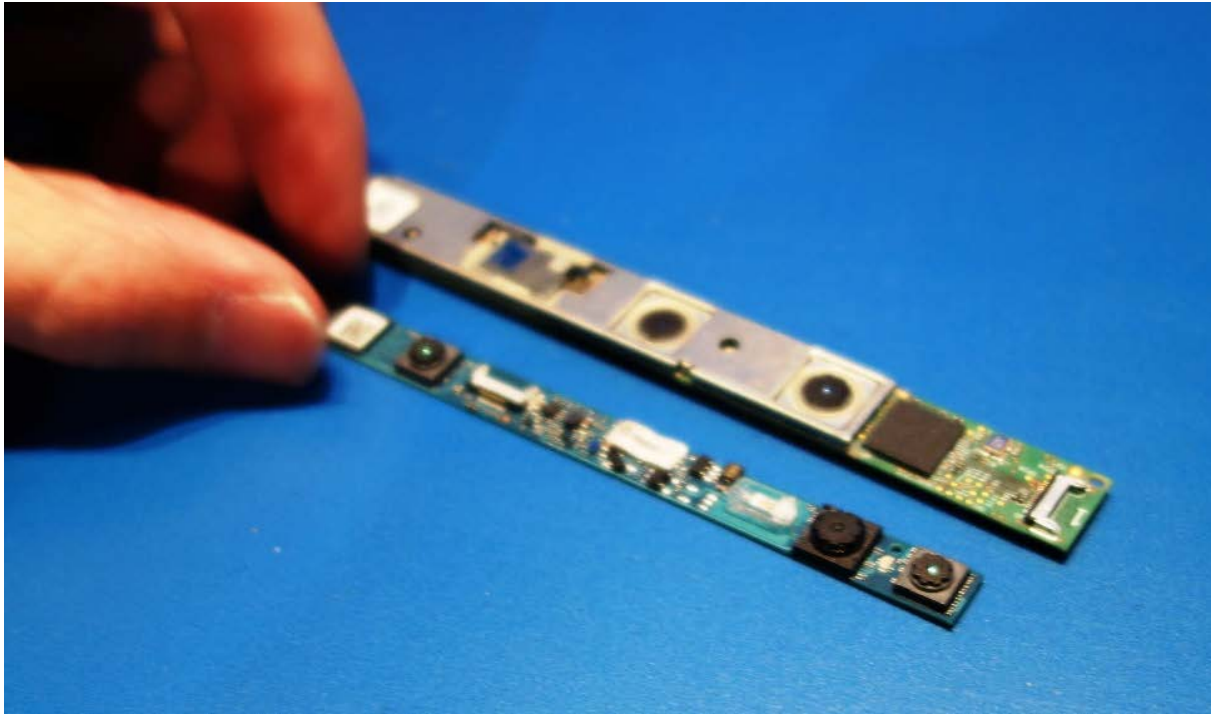
Login without a password...



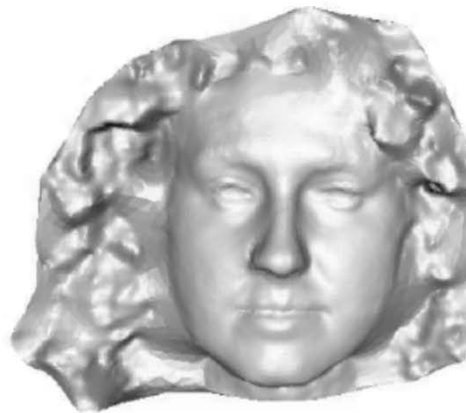
Login without a password...



Login without a password...



Single depth frame

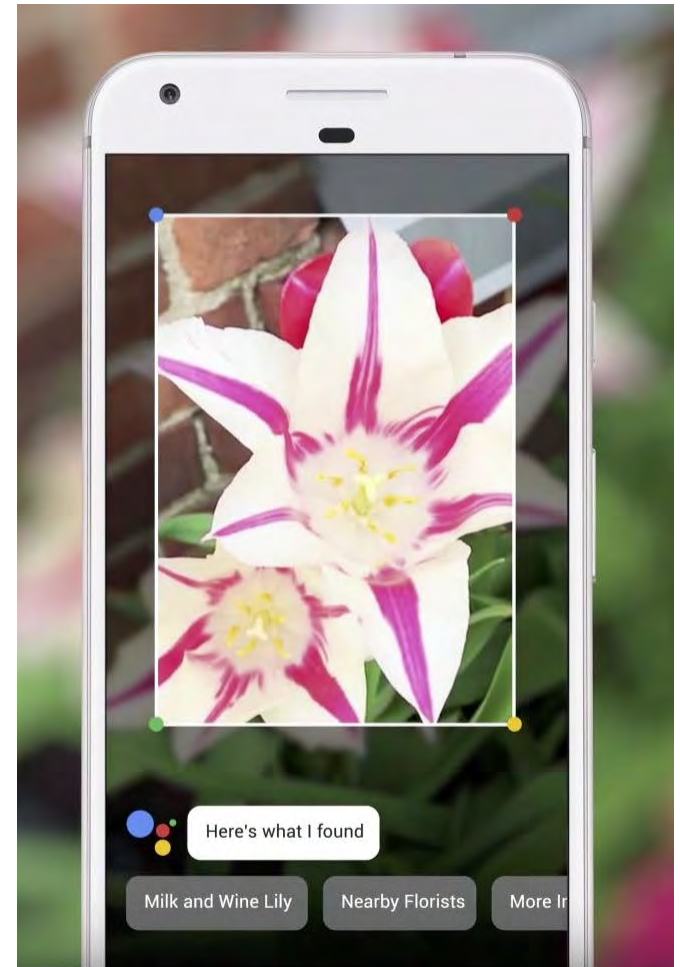
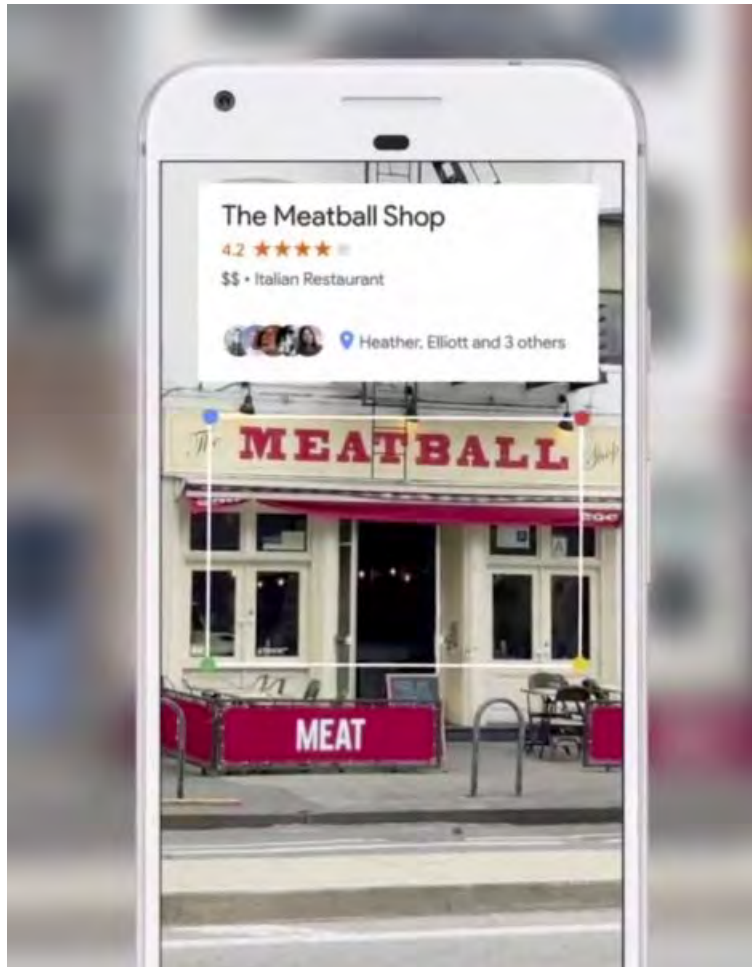


Reconstructed 3D mesh



Object recognition (in mobile phones)

e.g., Google Lens



Human shape capture



Human shape capture



Human shape capture



Human shape capture



Special effects: shape capture



Star Wars: Rogue One – Peter Cushing / Admiral Tarkin

Special effects: shape capture

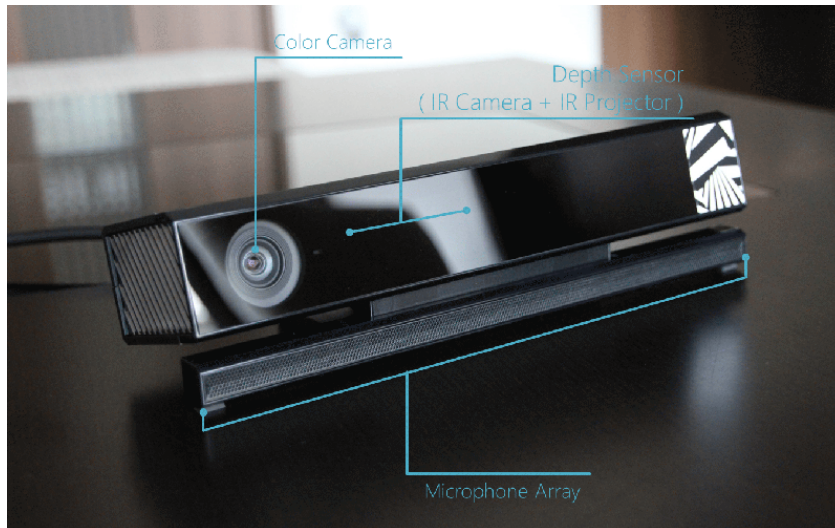


Special effects: motion capture



Interactive Games: Kinect

- Object Recognition: <http://www.youtube.com/watch?feature=iv&v=fQ59dXOo63o>
- Mario: <http://www.youtube.com/watch?v=8CTJL5IUjHg>
- 3D: <http://www.youtube.com/watch?v=7QrnwoO1-8A>
- Robot: <http://www.youtube.com/watch?v=w8BmgtMKFbY>



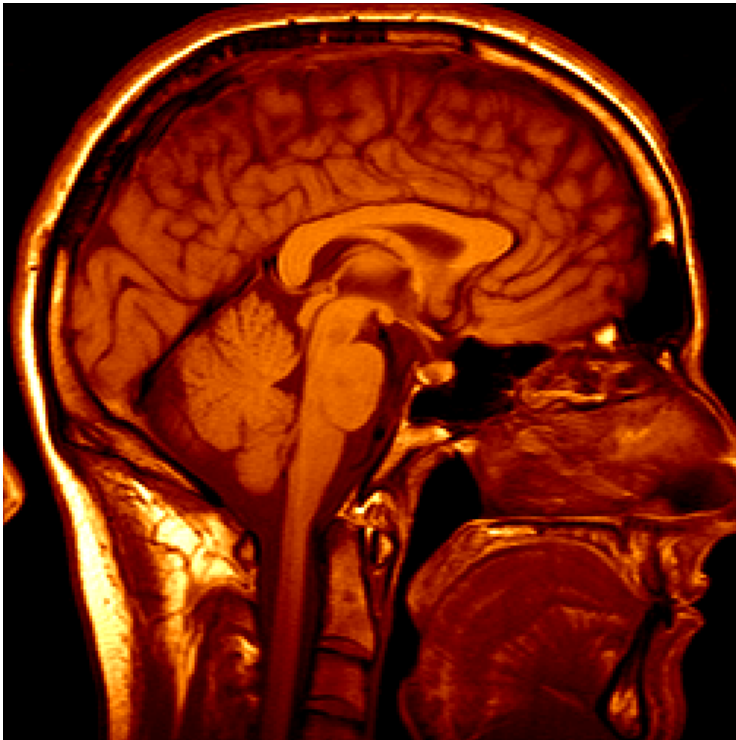
Sports



Sportvision first down line
Nice [explanation](http://www.howstuffworks.com) on www.howstuffworks.com

<http://www.sportvision.com/video.html>

Medical imaging



3D imaging
MRI, CT



Image guided surgery
[Grimson et al., MIT](#)

AutoCars - Uber bought CMU's lab







Industrial robots



Vision-guided robots position nut runners on wheels

Vision in space

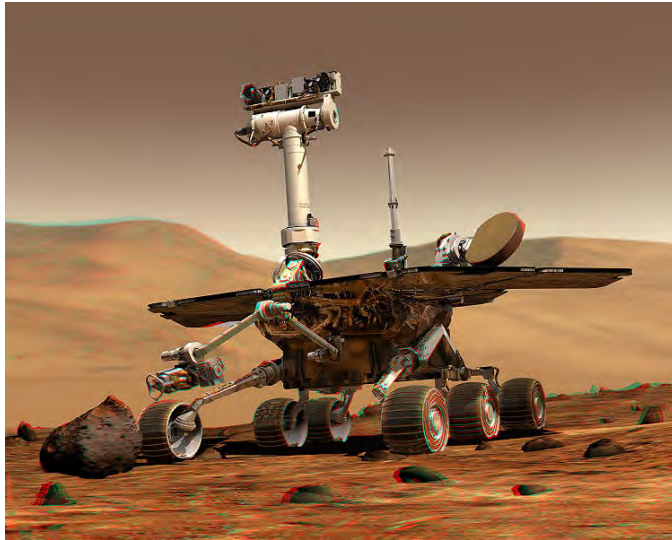


[NASA'S Mars Exploration Rover Spirit](#) captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision systems (JPL) used for several tasks

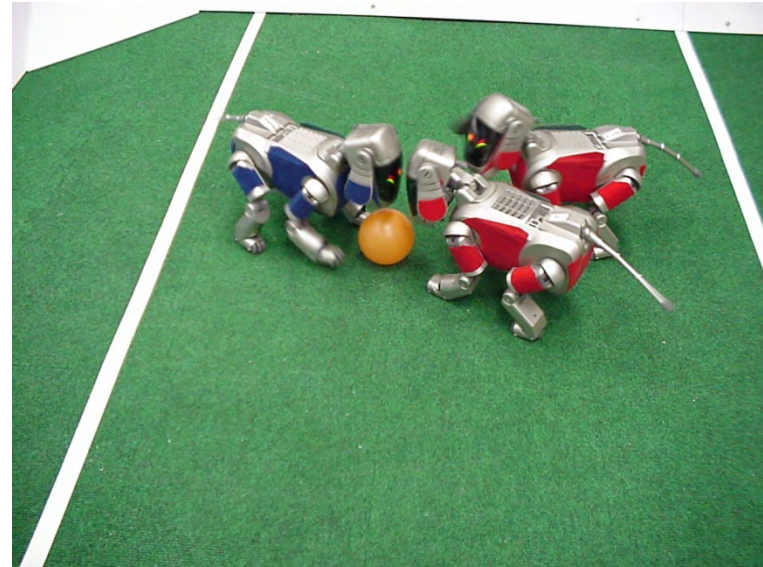
- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking
- For more, read “[Computer Vision on Mars](#)” by Matthies et al.

Mobile robots

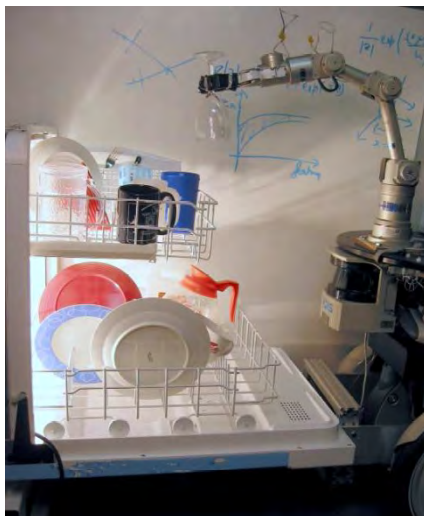


NASA's Mars Spirit Rover

http://en.wikipedia.org/wiki/Spirit_rover



<http://www.robocup.org/>

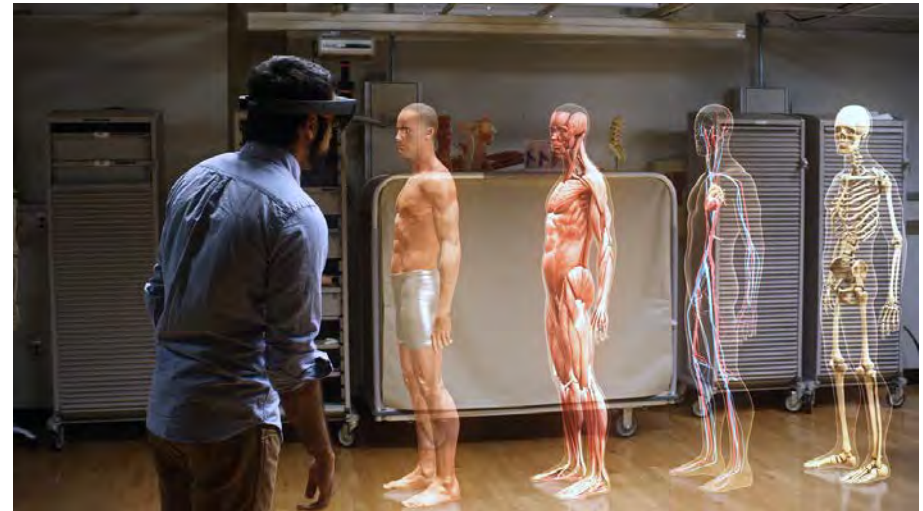


Saxena et al. 2008
[STAIR](#) at Stanford

amazon
Prime Air



Augmented Reality and Virtual Reality



MS HoloLens, Oculus, Magic Leap,
ARCore / ARKit

State of the art today?

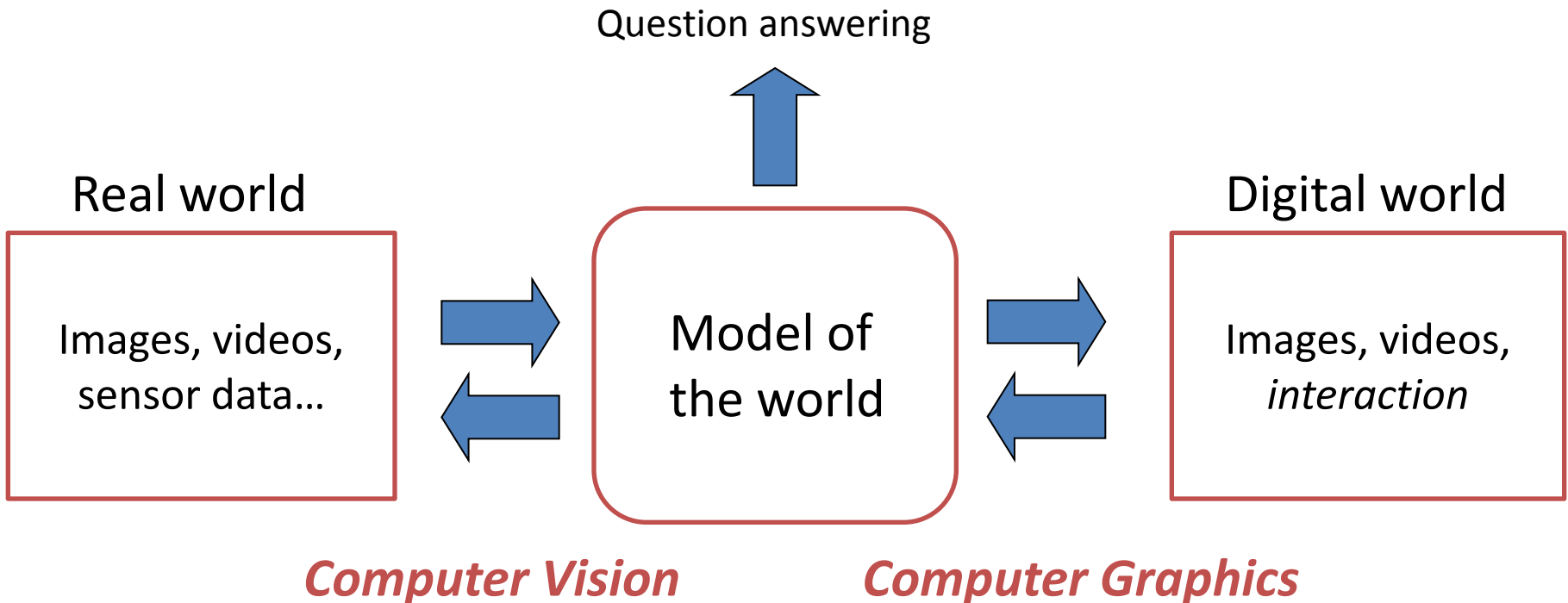
With enough training data, computer vision nearly matches human vision at most recognition tasks

Deep learning has been an enormous disruption to the field. Many techniques are being “deepified”.

Computer Vision and Nearby Fields

Derogatory summary of computer vision:

“Machine learning applied to visual data.”



Scope of CSCI 1430

Computer Vision

Robotics

Human Computer Interaction

Machine Learning

Image Processing
Recognition
Deep Learning
Geometric Reasoning

Medical Imaging

Graphics

Neuroscience

Computational Photography

Optics

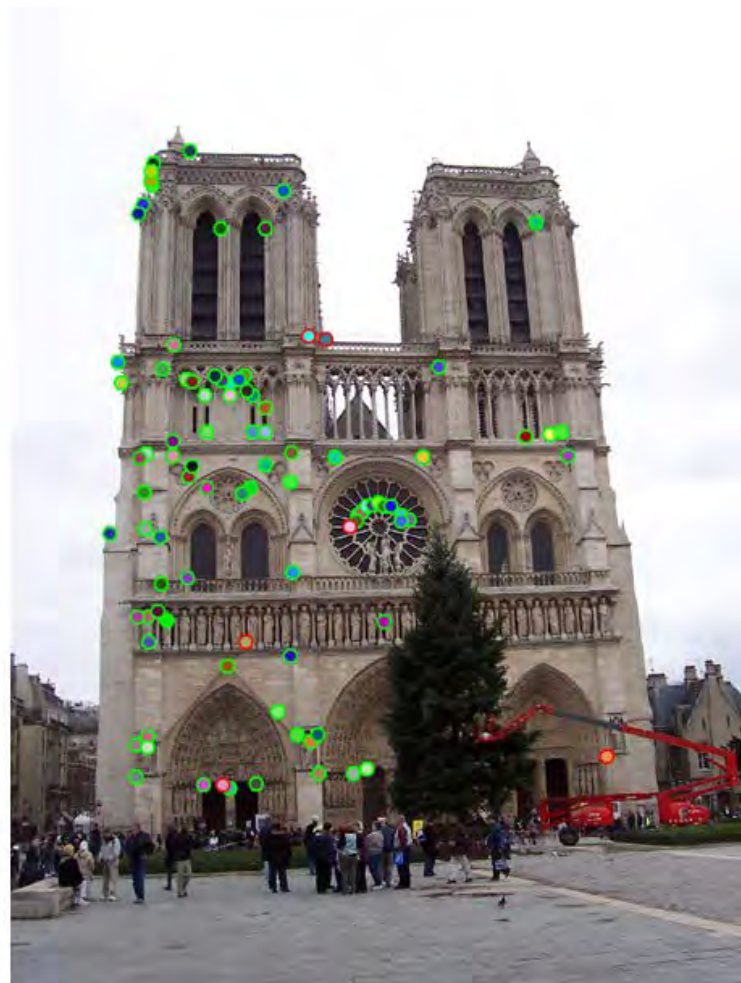
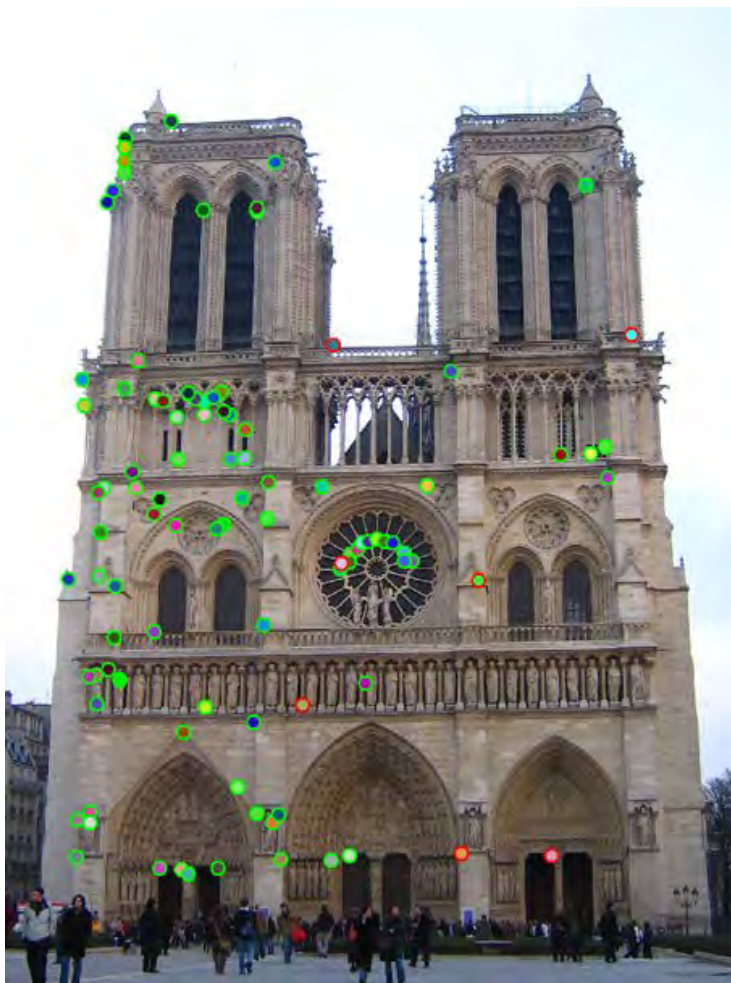
Proj 1: Image Filtering and Hybrid Images

- Implement image filtering to separate high and low frequencies.
- Combine high frequencies and low frequencies from different images to create a scale-dependent image.



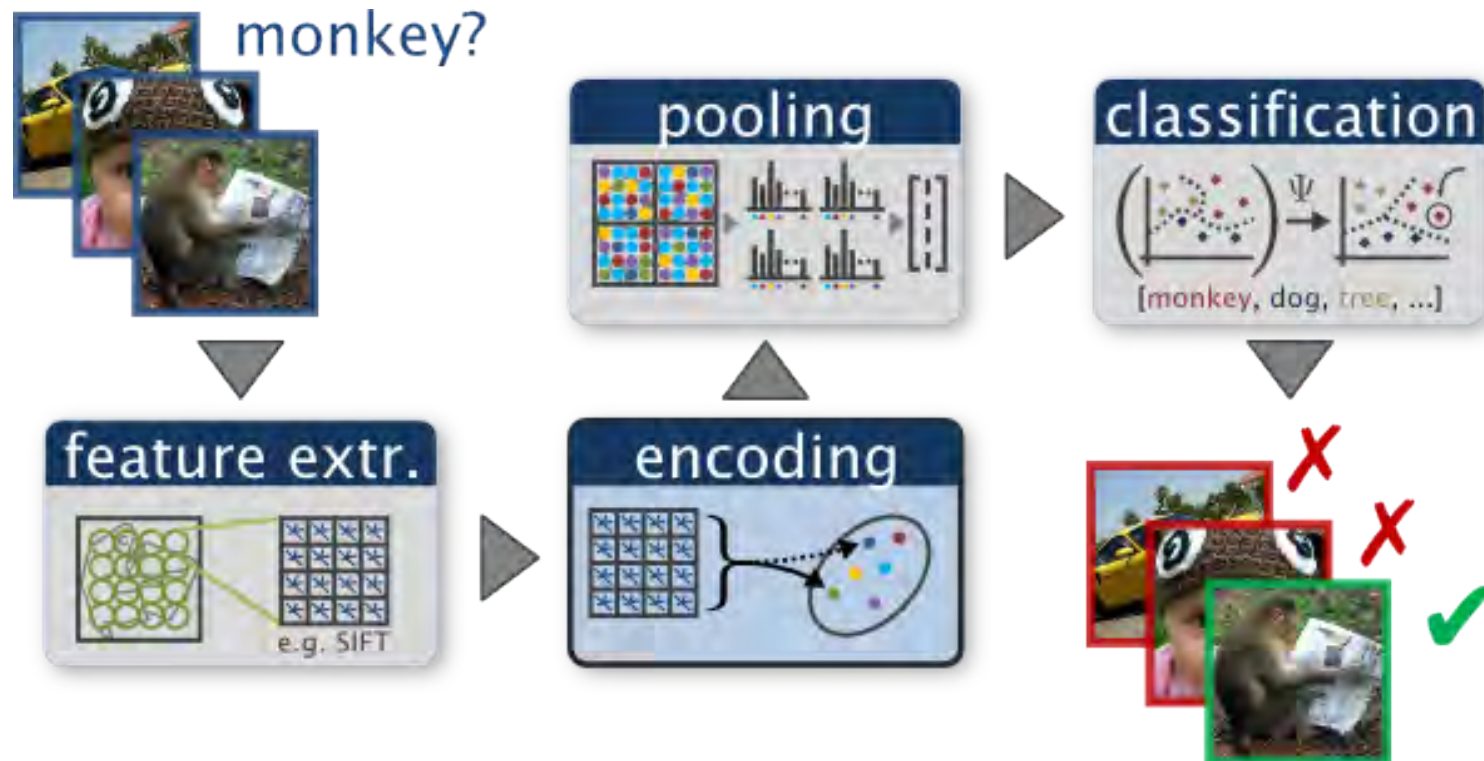
Proj 2: Local Feature Matching

- Implement interest point detector, SIFT-like local feature descriptor, and simple matching algorithm.



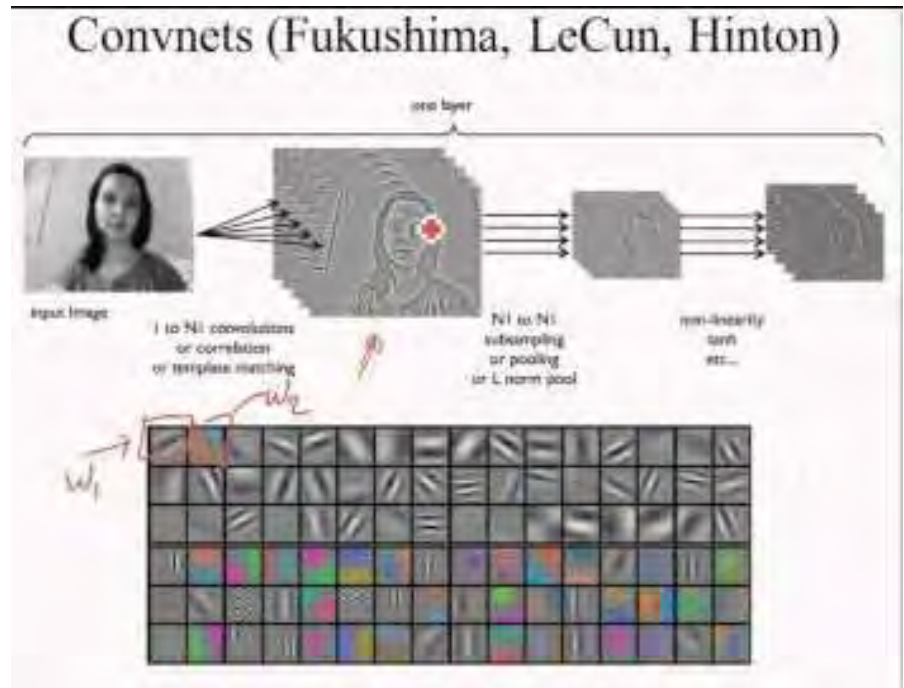
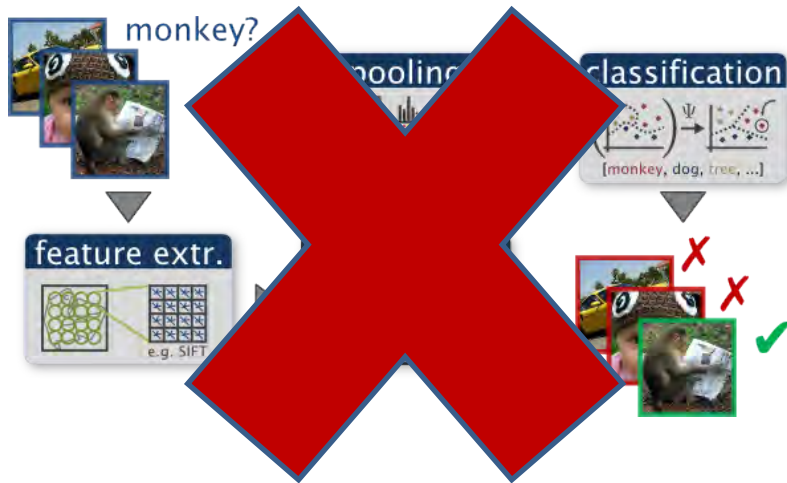
Proj 3: Scene Recognition with Bag of Words

- Quantize local features into a “vocabulary”, describe images as histograms of “visual words”, train classifiers to recognize scenes based on these histograms.



Proj 4: Convolutional Neural Nets

- Proj 3 again, but state of the art.



Proj 5: Multi-view Geometry

- Recover camera calibration from feature point matches.
- Foundation for almost all measurement in computer vision.



Proj 6: Group challenge

- Improve WebGazer:
A real-time Web-based eye tracker.

